

#### Department: Elec. Power and Machines Engineering Total Marks (electric part): 70 Marks



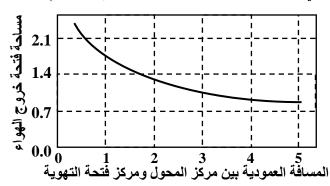
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Course Title: Electrical Installations Course Code: EPM4121 Year: forth year Date: January 2010 (First term) Allowed time: 3 hrs No. of Pages: (2)

#### Problem number (1) (15 Marks)

- وضح أسباب اختلاف المقاومة للتيار المستمر عن المقاومة للتيار المتردد في الكابلات مع ذكر العوامل التي تتوقف عليها هذه الأسباب
  - صمم حجرة خاصة لمحول 1600 ك.ف.أ. وحدد أبعاد فتحة التهوية بدون شبك علما بأن المحول سيوضع علي عوارض حديدية بارتفاع 70 سم. استخدم الجدول و المنحنى المرفقين.



ارتفاع جسم	الارتفاع	العرض	الطول	قدرة المحول
المحول (سم)	(سم)	(سم)	(سم)	ك.ف.أ.
100	195	102	185	630
160	280	140	220	1600
170	300	155	240	2000
180	325	170	260	3000

يراد حماية كابل ألمنيوم بطول 260م ومساحة مقطع 70 مم $^2$  باستخدام نبضية حماية مزودة بإعتاق مغناطيسي. فإذا كانت فولطية التشغيل تساوي 480 فولت ومساحة مقطع الحيادي تساوي نصف مساحة مقطع الوجه وقيمة الأعتاق المغناطيسي 1300 أمبير ويوجد 8 كوابل متساوية المقطع ومتصلة بالتوازي، بين ما إذا كان يمكن حماية الكابل عند جميع ظروف التشغيل. استخدم معاملات التصحيح من الجداول المرفقة.

V	220	400	415	440	480	500	660
$K_1$	0.58	1.05	1.11	1.16	1.26	1.31	1.73

عدد الكوابل	2	3	4	5	6
$K_2$	2	2.65	3	3.2	3.33

#### Problem number (2) (15 Marks)

أذكر أهم الاعتبارات التي يجب مراعاتها عند تنفيذ الإضاءة في الأماكن التالية: (5 درجات) المكاتب الخاصة 2- المستشفيات 3- القاعات الدراسية

بين إمكانية تغذية محرك أحادي 500 فولت بكابل نحاسي طوله 100م ومساحة مقطعه 35 مم 2 عند تيار تشغيل عادي 80 أمبير بمعامل قدرة 8.0 وتيار بدأ إقلاع 450 أمبير بمعامل قدرة 35%. أقصى فقد للفولطية مسموح به على أطراف المحرك 8%. فقد الفولطية في الكابل الرئيسي المغذي للوحة المحرك عند تيار التشغيل العادي = 6 فولت وتيار الكابل الرئيسي 600 أمبير. يمكنك استخدام جدول فقد الفولطية المرفق (فقد الفولطية بين الأطوار بالفولت/أمبير/كم للمحركات).

الثية الطور	دارة محركات ثلا	دارة محركات أحادية الطور		الكابل مم2	مقطعه
بدأ الإقلاع Cos φ = 0.35	تشغیل عادی Cos φ = 0.8	بدأ الإقلاع Cos φ = 0.35	تشغیل عادي Cos φ = 0.8	ألومونيوم	نحاس
0.65	1.3	0.75	1.5	35	25
0.52	1	0.6	1.15	50	35
0.41	0.75	0.47	0.86	70	50
0.32	0.56	0.37	0.64	120	70

بين أهمية التأريض للأجسام المعدنية المكشوفة ووضح تأثيره علي جهد الجسم المعدني المكشوف عند حدوث قصر 5 درجات)

**P.T.O.** Page: 1/2

	Good Luck	
Course Examination Committee  Dr. Ahmed Refaat	Dr. Mohamed Abo El Azm	
Dr. Saeed Allam	Prof. Mohamed Tantawy	
Course Coordinator: Dr. Ahmed Refaat		
		<b>Page:</b> 2/2



6)

c)

a)

قو ی عدید الا داء الدینا عبکی الألانا

Department: Elec. Power and Machines Engineering Total Marks: 70 Marks



Course Title: Electrical Machines Dynamics

Date: Feb. 3rd 2010 (First term)

Course Code: EPM4124

Allowed time: 3 hrs

Year: 4th

No. of Pages: (2)

Remarks: (answer the following questions... assume any missing data... answers should be supported by sketches if possible)

#### Question number (1) (22 Marks)

Derive a mathematical model by which the dynamic behaviour of a series dc motor can be a) predicted. Show how this model is transformed using Laplace transformation technique, then write down the model in the matrix form:  $[U_{input}] = [A][X_{output}]$ . (7 Marks)

Derive a mathematical model by which the dynamic behaviour of a separately excited do generator can be predicted under a constant speed operation. Setup the differential equations in the matrix form: [X] = [A][X] + [B][U]. (5 Marks)

Consider a separately excited dc generator with the following data:  $R_a = 0.15 \Omega$ ,  $L_a = 5 \text{ mH}$ ,  $R_f = 3$  $\Omega$ , L<sub>f</sub>= 0.5 H. Rated voltage = 220 V, rated armature current = 80 A and rated field current = 5 A. If the generator operates at a constant speed of 1500 rpm under rated conditions, answer the following:

Determine the transfer function of the generator voltage. (i)

(ii) Determine the voltage and the current variations as functions of time after a step increase of 10 percent in the field winding voltage.

(iii) Simplify, giving a suitable reason(s), the obtained voltage and current functions.

(iv) Determine the short circuit current as a function of time in the case of a sudden short circuit occurs across the armature at constant field current. (10 Marks)

#### Question number (2) (28 Marks)

Derive a detailed mathematical model by which the dynamic behaviour of a three-phase induction motor can be predicted in its natural abc-axis variables, then answer the following:

Write down, aiding with appropriate drawing(s), the transformation matrices required to transform the abc-axis model to an arbitrary reference frame qdo-axis model.

Derive an expression of the transformed qd-axis supply voltages as a function of time in

stationary, rotor and synchronous reference frames.

(iii) Write down a complete qdo-axis dynamic model valid to predict the dynamic performance of the three-phase induction motor in a synchronous reference frame. Draw the dynamic qdaxis equivalent circuit.

(iv) Show the necessary modification(s) that should be applied to the model obtained in (iii) to describe the dynamic behaviour of the three-phase induction motor in both stationary and rotor reference frames. (Do not write the model)

(v) Modify the model obtained in (iii) to be represented in per unit variables.

(vi) Show how the steady-state voltage equations of the three-phase induction motor can be obtained from the qdo-axis dynamic model represented in stationary, rotor and synchronous reference frames. (Do not write the equations)

(vii) Summarize the advantages and disadvantages of the abc-axis model and the qdo-axis model.

(20 Marks)

Der	rive an expression of the electromagnetic developed torque (expressed in qdo three-phase induction motor.	o-axis variables) (5 Marks)
Sho	ow the relation between the inertia constant and the rotor stored energy	(3 Marks
	Question number (3) (20 Marks)	
Der mac	rive the expressions of both self and mutual inductance of the salient- chine.	pole synchronou (5 Marks)
dire (i) (ii) (iii) (iv)	describe the dynamic behaviour of this machine when it operates as a general	g:  ttrices required to  frame.  ynamic behaviou  raw the dynami  obtained in (ii) to  rator,  pole synchronous  ted in the roto
	ve a linearized mathematical model by which the dynamic behaviour of a thr	(10 Marks)
)eri	synchronous generator, having no damper windings, can be predicted whe	ree-phase salient

# WITH MY BEST WISHES

Dr. Said M. Allam

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#### Department: Electronics & Comm. Engineering Total Marks:



Faculty Faculty of Engineering

Course Title: Electric Communications

Date: January 2010 (First term)

Course Code: Allowed time: 3 hrs Year: 4th

No. of Pages: (2)

Remarks: (answer the following questions... assume any missing data... answers should be supported by sketches...etc)

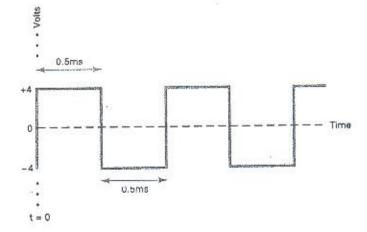
#### Question number (1)

- a) Explain the difference between external and internal noise
  - b) Calculate the noise power at the input of a receiver with an equivalent noise temperature of 45 K. Its fed from an antenna with a 35 K equivalent noise temperature and operates over a 5 MHz bandwidth ( $k=1.38\times10^{-23}$  J/K).

#### Question number (2)

- a) A multistage system has six stages of gain from input to output .The power gains are 6, 3,10, 4, 9 and 12 dB. What is the overall gain in dB? What is the power of the output signal when the input is 0.15 W?
- b) For the train of square waves shown in Fig.1
- (i) Determine the peak amplitudes and frequencies of the first four odd harmonics
- (ii) Draw the frequency spectrum
- (iii) Calculate the total instantaneous voltage for several times and sketch the time domain waveform

Fig. 1



#### Problem number (3)

- a) (i) Explain the difference between single tuned transformers and double tuned transformers.
  - (ii) Determine the overall bandwidth for :
    - Two single tuned amplifiers each with a bandwidth of 10 kHz.
    - Three single tuned amplifiers each with a bandwidth of 10 kHz.
    - A double-tuned amplifiers with optimum coupling, critical coupling of 0.02 and a resonant frequency of 1 MHz
- b) Prove that the power of the carrier is unaffected by the AM modulation process

## Question number (4)

- (a) Sketch the block diagram of a PLL frequency synthesizers and explain its operation.
  - (b) A double -conversion receiver uses a 30 MHz first IF to receive 104 MHz signals, with an LO above the received frequency. What is the image frequency? If the receiver has a second IF at 10.7 MHz, with the second LO also above the input frequency. What is the possible image frequency for the second IF? What would the image frequency be if a single conversion receiver with 10.7 MHz IF and high tracking LO were used?

## Question number (5)

- a) Sketch the block diagram of AM superheterodyne receiver and explain its operation.
- b) Sketch the SSBSC FDM system block diagram and explain its operation .

#### Good Luck

## Course Examination Committee

Prof. Mustafa M.Abd Elnaby Dr. Heba Elkhoby

Prof. Mohamed Nasr Dr. Abd Elfatah Abohashem

Course Coordinator: Prof. Mustafa Mahmoud Abd Elnaby



## ع فنوى حد من Department: Electrical Power and Machines Engineering Total Marks: 85 Marks

Faculty of Engineering

Course Title: Power System Protection Date: Jan 30th 2010 (First term)

Course Code: EPM41 Allowed time: 3 hrs

Year: 4th No. of Pages: (2)

Answer the following questions

# Problem number (1)

(25 Marks)

What is protective relaying? Explain the various functions of protective relaying? State the methods used for fault detection? (6 Marks)

What is the protective zone? Why the protective zones are arranged in overlap fashion? With the help of simple diagram, show how the zones are overlap? (6 Marks)

Explain what is meant by primary protection and backup protection? State the various me ho is used to provide backup protection? (6 Mark ;)

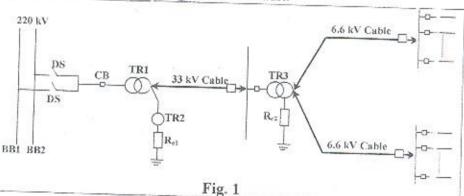
In the part of the network shown in Fig. 1:

(7 Marks)

Determine the zones of protection.

Suggest relays used along the system to protect it against earth fault.

TR1: 220 MVA, 220/33 kV, Ynd11, %Z = 13%. TR2: 40 MVA, 33/6.6 kV, Dyn I 1, %Z = 10%. TR3: 300 kVA, 33/33 kV, Zigzag, %Z = 13%, used as earthing transformer.



## Problem number (2)

(20 Marks)

Explain the following terms related to protective relays:

i) Pickup

.1

3)

1)

1

ii) Dropout or Resct

(5 Marks)

iv) Time setting multiplier

v) Relay burden

iii) Plug setting multiplier

vi) Overreach

Describe any one type of electromagnetic attracted armature type?

(5 Marks)

Explain with the help of neat sketch, the construction and working of directional induction type (5 Mark)

Describe the operation of the following relays with neat sketch:

(6 points)

Balance beam relay used as plain impedance relay.

Balance beam relay used as plain directional relay.

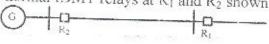
Induction disc overcurrent relay.

Problem number (3)

(20 Marks)

What is IDMT characteristic of a relay? What is the procedure of setting IDMT relay? What initial data is required? How is the directional relay different than simple IDMT relay? (5 Marks)

Choose time settings for the normal IDMT relays at R<sub>1</sub> and R<sub>2</sub> shown in Fig. 2



2000A

1000A

Fig. 2.

Phase fault currents are shown.

Load current, through  $R_2 = 200A$ , and through  $R_1 = 75A$ .

CT ratio at  $R_2 = 200/5$  and at  $R_1 = 100/5$ .

Plug setting are in steps of 25% to 200%.

The time-current characteristic of the relay is given in the following table

Plug Setting Wultiplier	2	3	5	10	1.4	
			3	10	15	20
Time for TS of I (sec)	10	6	41	3	25	2.0

Simple time graded overcurrent relays are applied to a 5 bus ring main (single feed point). Circuit breakers are connected at each side of each bus. Choose time delays for each ovecurrent relay and indicate which relays need to be directional.

(8 Mark i)

#### Problem number (4)

1)

(20 Marks)

(7 Mark ;)

Explain what is meant by distance protection. What arrangement is made to make the relay measure positive sequence impedance only for single line to ground fault (SLG)? (5 Marks)

Explain why second zone of distance relay can be omitted in some cases and what's happen in this situation.

(5 Mark;)

Consider the multi-terminal line in the system shown in Fig. 3. Each of the buses C, D, G, H and J has a source of power behind it. For a three-phase fault on bus B, the contributions from each of the sources are as follows:

Source	Current
	600
C	200
D	300
G	800
H	400

You may assume that the fault current contributions from each of these sources remain unchanged as the fault is moved around throughout the system shown. Determine the zones 1, 2 and 3 settings for the distance relay at bus A. Remember to take into account the effect of the infect for determining the zones 2 and 3 settings, while no infeeds are to be considered for the zone 1 settings.

#### Good Luck

## Course Examination Committee

Dr. Mohamed Abo Elazm

Dr. I Bedir

Dr. A. Azmy



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1

Department: Electrical Power and Machines Engineering Total Marks: 85 Marks



Course Title: Power System Protection

Course Code: EPM41

Year: 4th

Date: Jan 30th 2010 (First term)

Allowed time: 3 hrs

No. of Pages: (2)

# Answer the following questions

## Problem number (1)

(25 Marks)

What is protective relaying? Explain the various functions of protective relaying? State the (6 Marks)

What is the protective zone? Why the protective zones are arranged in overlap fashion? With the help of simple diagram, show how the zones are overlap? (6 Marks)

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In the part of the network shown in Fig. 1:

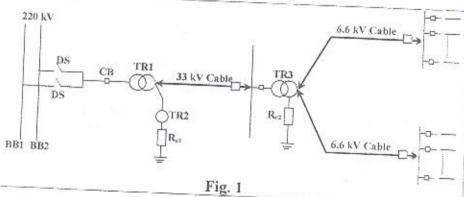
(7 Marks)

Determine the zones of protection.

Suggest relays used along the system to protect it against earth fault.

TR1: 220 MVA, 220/33 kV, Ynd11, %Z = 13%. TR2: 40 MVA, 33/6.6 kV, Dyn11, %Z = 10%.

TR3: 300 kVA, 33/33 kV, Zigzag, %Z = 13%, used as earthing transformer.



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(20 Marks)

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i) Pickup iv) Time setting multiplier

1

0)

1)

ii) Dropout or Reset

v) Relay burden

(5 Marks) iii) Plug setting multiplier

vi) Overreach

Describe any one type of electromagnetic attracted armature type?

(5 Marks)

Explain with the help of neat sketch, the construction and working of directional induction type (5 Mark )

Describe the operation of the following relays with neat sketch:

(6 points)

Balance beam relay used as plain impedance relay.

Balance beam relay used as plain directional relay.

Induction disc overcurrent relay.

Problem number (3)

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Fig. 2.

Phase fault currents are shown.

Load current, through  $R_2 = 200A$ , and through  $R_1 = 75A$ .

CT ratio at  $R_2 = 200/5$  and at  $R_1 = 100/5$ . Plug setting are in steps of 25% to 200%.

The time-current characteristic of the relay is given in the following table

Plug Setting Wultiplier	-		III the 1011	- Tana		
	- 2	3	5	-10	15	20
Time for TS of 1 (sec)	10	6	4.1	-	7.5	20
	10	0	4.1	3	2.5	2.2

Simple time graded overcurrent relays are applied to a 5 bus ring main (single feed point ). Carcuit breakers are connected at each side of each bus. Choose time delays for each ovecurrent relay and indicate which relays need to be directional. (8 Mark :)

Problem number (4)

3)

(20 Marks)

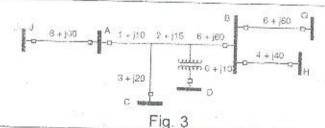
(7 Marks)

Explain what is meant by distance protection. What arrangement is made to make the relay measure positive sequence impedance only for single line to ground fault (SLG)? (5 Marks)

Explain why second zone of distance relay can be omitted in some cases and what's happen in this (5 Marks)

Consider the multi-terminal line in the system shown in Fig. 3. Each of the buses C, D, G, H and J has a source of power behind it. For a three-phase fault on bus B, the contributions from each of the sources are as follows:

Source	Current
J	600
C	200
D	300
G	800
Н	400



You may assume that the fault current contributions from each of these sources remain unchanged as the fault is moved around throughout the system shown. Determine the zones 1, 2 and 3 settings for the distance relay at bus A. Remember to take into account the effect of the infect for determining the zones 2 and 3 settings, while no infeeds are to be considered for the zone 1 (10 Marks)

## Good Luck

Course Examination Committee

Dr. Mohamed Abo Elazm

Dr. I Bedir

Dr. A. Azmy



#### Department: Elec. Power and Machines Engineering Total Marks: 60 Marks



Course Title: Electrical Testing and Measurements (1) Date: Jan. 25th 2010 (First term)

Course Code: EP4104 Allowed time: 3 hrs

Year: 4th

No. of Pages: (1)

Remarks: (answer the following questions... assume any missing data... answers should be supported by sketches if possible)

Question number (1) (12 Marks)	
Show why the starting current of three phase induction motor is higher the Explain the different techniques used to decrease this current.	nan the rated curren (6 Marks)
What is a star-delta switch? Can it be used for any type of induction connection diagram of this switch.	n motors? <b>Draw</b> th (6 Marks)
Question number (2) (12 Marks)	
What are the different techniques used to control the speed of the three phe Explain the limitations of using each one experimentally.	ase induction motor (6 Marks)
Sketch and explain the shape of an induction motor torque-speed charact how the different speed control techniques affect the torque-speed charact phase induction motor.	eristics curve. Show teristics of the thre (6 Marks)
Question number (3) (12 Marks)	
Write down the conditions for connecting two synchronous generators in pa happens if one of these conditions is not achieved. Show how each o experimentally.	ne can be achieve
happens if one of these conditions is not achieved. Show how each o	rallel. Explain wha ne can be achieve (12 Marks)
Appens if one of these conditions is not achieved. Show how each of experimentally.  Ouestion number (4) (12 Marks)  Explain in details how the equivalent circuit parameters of a single phase indetermined experimentally. Draw the equivalent circuit in each test measuring instruments.	ne can be achieve (12 Marks)
Appens if one of these conditions is not achieved. Show how each of experimentally.  Question number (4) (12 Marks)  Explain in details how the equivalent circuit parameters of a single phase indicates the determined experimentally. Draw the equivalent circuit in each test	ne can be achieve (12 Marks)  duction motor can b with appropriat
Appens if one of these conditions is not achieved. Show how each of experimentally.  Ouestion number (4) (12 Marks)  Explain in details how the equivalent circuit parameters of a single phase indicatermined experimentally. Draw the equivalent circuit in each test measuring instruments.	ne can be achieve (12 Marks)  duction motor can b with appropriat (12 Marks)
Appens if one of these conditions is not achieved. Show how each of experimentally.  Question number (4) (12 Marks)  Explain in details how the equivalent circuit parameters of a single phase include determined experimentally. Draw the equivalent circuit in each test measuring instruments.  Question number (5) (12 Marks)  Show why a synchronous motor can not start by itself. What are the technique type of motor.  Explain what happens to a synchronous motor as its field current is varied. Synchronous motor V curves can be obtained experimentally. Illustrate suitable drawing(s).	duction motor can b with appropriat (12 Marks)  (12 Marks)  ues used to start thi (4 Marks)  Show in details how
Appens if one of these conditions is not achieved. Show how each of experimentally.  Question number (4) (12 Marks)  Explain in details how the equivalent circuit parameters of a single phase include determined experimentally. Draw the equivalent circuit in each test measuring instruments.  Question number (5) (12 Marks)  Show why a synchronous motor can not start by itself. What are the techniq type of motor.  Explain what happens to a synchronous motor as its field current is varied. Synchronous motor V curves can be obtained experimentally. Illustrate	duction motor can b with appropriat (12 Marks)  ues used to start thi (4 Marks)  Show in details how e your answer with



a)

b)

c)

a)

#### Department: Elec. Power and Machines Engineering Total Marks: 75 Marks



Faculty of

Course Title: Application of Computer in Electrical Power Systems Course Code: EPM4119 Date: January 25th 2010 (First term)

Year: 4th

Allowed time: 3 hrs

No. of Pages: (2)

Remarks: (answer the following questions... assume any missing data... answers should be supported by sketches...etc)

#### Problem number (1)

Deduce the admittance matrix model of tapping transformer, then sketch its equivalent circuit. Define The following terms. (i) graph; (ii) tree; (iii) Cotree; (iv) branch; (v) link

Prove that the relation that used to insert new link between two old buses p and q in impedance bus matrix can be evaluated from:

$$Z_{bus}^{new} = Z_{bus}^{old} - \frac{\Delta Z \Delta Z^T}{Z_{II}}$$

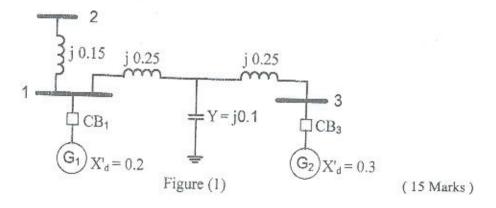
Where; 
$$Z_{II} = z_{pq} + Z_{pp} + Z_{qq} - 2Z_{pq}$$
  

$$\Delta Z = \begin{bmatrix} Z_{1q} - Z_{1p} \\ Z_{1q} - Z_{1p} \\ \vdots \\ Z_{-q} - Z_{-q} \end{bmatrix}$$

## Problem number (2)

(30 Marks)

For system shown, (i) find bus impedance matrix; (ii) find rating of CB1 and CB3, if bus voltages is I p.u.; (iii) if solidly three-phase fault occurred at bus 1, find bus voltages during fault and current between buses.



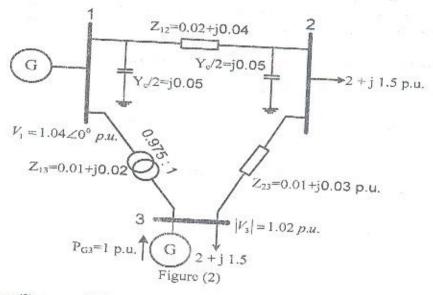
(i) For system shown in Figure (1), using Fast decoupled method, start with initial estimates of  $V_2^0 = 1 \angle 0^0 \ p.u.$  and  $V_3^0 = 1.02 \angle 0^0 \ p.u.$ , Calculate the bus voltage magnitudes and their angles at bus 2 and 3 (only 2 iteration required).

P. T. O.

Page 1/2

b)

(ii) If after several iteration  $V_2=0.988\angle -1.9889^0$  p.u. and  $V_3=1.02\angle -1.1106^0$  p.u., find the active and reactive power losses through line between bus 1 and 2, active and reactive power generation at slack bus and reactive power generation at voltage control bus.



Problem number (3) (30 Marks)

a)

b)

C)

Put ☑ or ☑ against the number of the following sentences then correct the false sentences (15 Marks)

The Gauss-Seidel method is a stable method for power flow solution.

- The active and reactive power generations at regulated buses must be known before power flow solutions
- The time required for one iteration in decoupled method is smaller than that required for fast-decoupled
- The line to ground fault is important for determining the short circuit capacity of circuit breakers.
- The fast decoupled method is the more sophisticated method for power flow solution.
- In symmetrical three-phase system, negative and zero sequence is zero.
- The more stable method of power flow solution is Newton-Raphson method.
- Reactors are used at varies points in electrical power system to limit short circuit current. The grounding is generally done at the supply end.

10 The Jacobian matrices are fixed and independent in iteration number in decoupled method

Sketch the rotor power angle of synchronous machine versus time for stable and unstable operations.

(i) Write down an algorithm of Gauss-Zeidel method of power flow solution.

(ii) Write down a MATLAB program that used to evaluate the fault current due to three-phase

(With My Best Wishes) Dr. Ibrahim Bedir



## Department: Elec. Power and Machines Engineering Total Marks (electric part): 70 Marks



Course Title: Electrical Installations Date: January 2010 (First term)

Course Code: EPM4121 Allowed time: 3 hrs

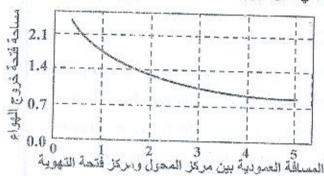
Year: forth year No. of Pages: (2)

-1

## Problem number (1) (15 Marks)

رضح أسباب اختلاف المقاومة للتيار المستمر عن المقاومة للتيار المتردد في الكابلات مع ذكر العوامل التي تتوقف المياب اختلاف المقاومة للتيار المستمر عن المقاومة للتيار المتردد في الكابلات مع ذكر العوامل التي تتوقف

، سمر حجرة خاصة لمحول ١٦٠٠ ك.ف. أ. وحدد أبعاد فتحة التهوية بدون شبك علما بأن المحول سيوضع على على المورض حديدية بارتفاع ٧٠ سم. استخدم الجدول و المنحني المرفقين.



ارتفاع جسم المحول (سم)	الإرتفاع (سىم)	العرض (سم)	الطول (سم)	قدرة المحول كرة إلى
1	190	1.4	110	37.
17.	YA .	1 .	Y Y .	17
14.	4	100	Y 2 .	Y
1/.	440	17.	77.	

براد حماية كابل المنيوم بطول ٢٦٠م ومساحة مقطع ٧٠مم باستخدام نبضية حماية مرودة بإعتاق مغناطيسي. فإذا كانت قولطية التشغيل تساوي ٤٨٠ فولت ومساحة مقطع الحيادي تساوي نصف مساحة مقطع الوجه وقيصة الأعتاق المغنادليسي ١٣٠٠ امبير ويوجد ٣ كوابل متساوية المقطع ومتصلة بالتوازي، بين ما إذا كان يمكن حماية الكابل عند جميع ظروف التشغيل. استخدم معاملات التصحيح من الجداول المرفقة.

V	220	400	415	440	480	500	660
$K_1$	0.58	1.05	1.11	1.16	1.26	1.31	1.73

عدد الكوابل	2	3	4	5	5
$K_2$	2	2.65	3	3.2	3.33

# Problem number (2) (20 Marks)

الكر أهم الاعتبارات التي يجب مراعاتها عند تنفيذ الإضاءة في الأماكن التالية: (٥ درجات) الكاصة ٢- المستشفيات ٢- المستشفيات ١٠- العاصة الدراسية

بين إمكانية تغذية محرك أحادي ٥٠٠ فولت بكابل نحاسي طوله ١٠٠ م ومساحة مقطّعه ٣٥ مم ٢ عند تيار تشغيل عادي ٨٠ أمبير بمعامل قدرة ٣٥ %. أقصى فقد للفولطية مسموح به عادي ٨٠ أمبير بمعامل قدرة ٣٥ %. أقصى فقد الفولطية مسموح به على أطراف المحرك ٨٠ . فقد الفولطية في الكابل الرئيسي المعذي للوحة المحرك عند تيار التشغيل العادي ٣٠ على أطراف المدرك المنابل الرئيسي ٢٠٠ أمبير. يمكنك استخدام جدول فقد الفولطية المرفق (فقد الفوظية بين الأطوار ١٠٠ أمبير ٢٠٠ أمبير مكنك استخدام جدول فقد الفولطية المرفق (فقد الفولطية).

دارة محركات ثلاثية الطور		دية الطور	مقطعه الكابل مم ٢		
پدا الإقلاع Cos ф = 0.35	تشغیل عادی Cos φ = 0.8	بدأ الإقلاع Cos φ = 0.35	تشغیل عادی Cos φ = 0.8	الومونيوم	نحاس
٠,٠٥	1.4"	•.Vo	1.0	10	70
	1	1.1	1.10	٥,	40
٠.٤١	1.70	* . £ Y	7 1. 1	٧.	0.
• . "."	107	* . *V	47.	14.	٧.

يون أهمية التاريض للأجسام المعدنية المكشوفة ووضح تأثيره على جهد الجسم المعدني المكشوف عند حدوث قصر (٨ درجات)

P.T.O.

# Problem number (3) (20 Marks)

Define the planning phase of switchgear installation.

(5 points)

What are the main functional requirements for each of: busbar – circuit breaker – disconnector switch – load break switch? (5 points)

State the types of cooling used for power transformers.

(5 points)

Aided with clearly drawings, state the types of busbar layout.

(5 points)

# Problem number (4) (15 Marks)

A cement plant is supplied from 220 kV grid. Supplying will happen by opening an OHTL passing at a distance of 700 m from the plant. The substation will be a double busbar, air-insulated system and two step down 40 MVA transformers. Transformers are used to step down the voltage to 11 kV for using within the plant. For the abovementioned system, answer the following points:

- a) Determine the number of towers required from the opening point to the substation
- b) Determine the number of bays required for this substation.
- c) Determine the area required for this substation
- d) Draw the single-line diagram for this substation
- e) Draw the layout of the high voltage equipments in the substation yard.

# Good Luck

## Course Examination Committee

Dr. Ahmed Refaat Dr. Saeed Allam

a)

b)

c)

d)

Dr. Mohamed Abo El Azm Prof. Mohamed Tantawy

Course Coordinator: Dr. Ahmed Refaat

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# قوى كهربية قديم



### Electrical Power and Machines Department Total Marks: 85 Marks

Code: EP4103

First Term Pages: 2



Faculty of Engineering

# Course: Especial Machines Third Year

Time: 3:00 hrs Date: Jan 27, 2010

ANSWER THE FOLLOWING QUESTIONS, ASSUME ANY MISSING INFORMATION AND SUPPORT YOUR ANSWER WITH DIAGRAMS AND SKETCHES

Qu	estion 1: Marks:	25				
a.	Describe four different methods for starting of single phase induction motor. Support your answer with connection diagrams. Compare between the					
	Show the difference between the methods used for the starting of single-phase induction motor.					
b.	A 1/4hp, $1\phi$ , 120V, 60Hz, 1730rpm induction motor has stator winding resistance $R_1$ =2.9 $\Omega$ , magnetizing reactance $X_{mag}$ =55.72 $\Omega$ , and rotor resistance and leakage reactance referred to stator $R_2$ =2.7 $\Omega$ , $X_2$ =3.26 $\Omega$ . The rotational loss is 72.94W. Determine:					
	(a) input current (b) input power factor					
	(c) developed torque (d) Output power					
	(e) Efficiency.					
	The stator leakage reactance is assumed equal to the rotor leakage reactance referred to stator.					
Que	estion 2: Marks:					
a.	Compare between each pair of the following:	[6]				
	<ol> <li>Soft shopping and hard chopping</li> </ol>					
	Pulse width modulation and current regulation					
b.	Define each of the following quantities:	[4]				
	1. Detent torque					
	2. Position sensor					
C.	Explain the principle of operation and main characteristics of the following machines:					
	1. Universal Motor	[10]				
	2. Synchronous reluctance motor					
	Support your answer with necessary diagrams and graphs.					
–ه Que	estion 3: Marks:	20				
a.	State the difference between the drive circuits needed for operation of variable	20				
	reluctance and permanent magnet steeper motors.	[6]				

- Describe the principle of operation of hybrid steeper motors. Use two stacks-8/6 [6]
   hybrid steeper motor to explain your answer and provide necessary diagrams.
- c. A variable reluctance stepping motor has 40 stator teeth, 50 rotor teeth. It is driven at 400 pulses per second. Determine (a) step angle (b) resolution (c) motion speed (d) Number of pulses required to rotate the shaft through 54°.

#### Question 4:

Marks: 20

- a. Compare between switched reluctance machine and stepper motor from the point of view of operation, construction and power electronics required.
- Explain the effect of switching-on and switching-off angles on the current wave form and produced torque of switched reluctance motor.
- c. A three phase 6/4 VRM has stator pole angle  $\beta$ =30°, rotor pole angle  $\alpha$ =34°, air gap [10] length g=3×10<sup>-2</sup>cm, active length=8cm. The stator and rotor iron can be considered to be of infinite permeability.
  - Defining the zero of rotor angle at the position of phase-1 full alignment, plot with labels the inductance of the three phases' variation against rotor position.
  - Find the current of phase-1 required to produce flux density of 1.0T when phase-1 is in the position of maximum inductance. Make any required assumptions.

WITH BEST WISHES